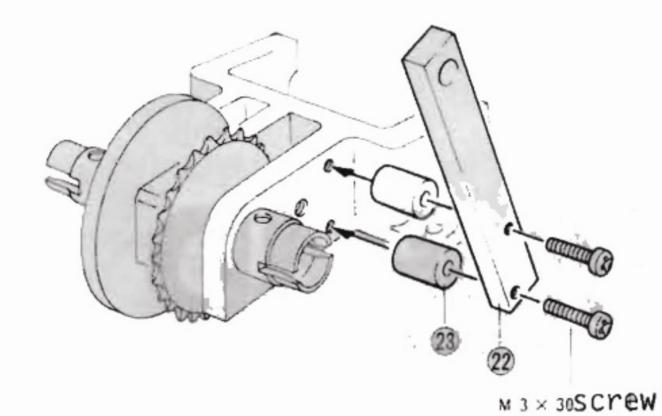


## AND JUMP 4D

SUPPLEMENTARY INSTRUCTION

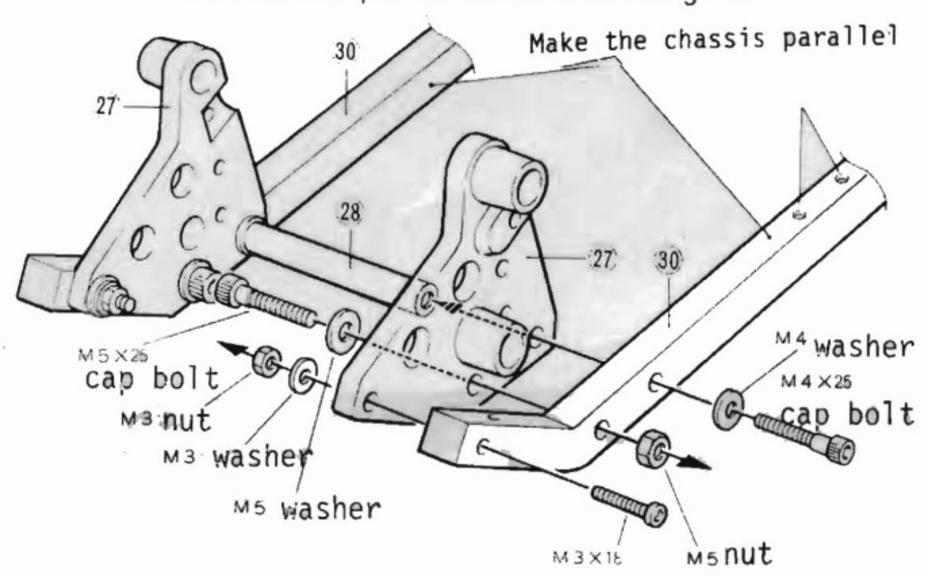




10 Install collar 23 together with muffler installation bracket 20.

## 12

## no.12-16 parts in front B bag



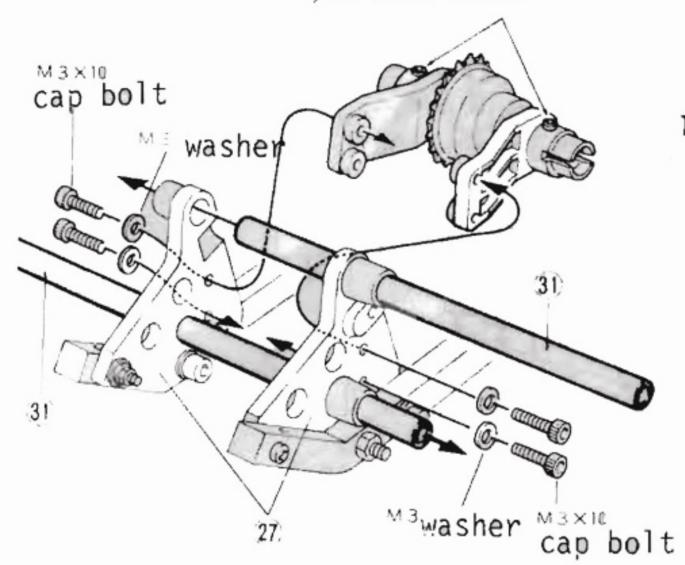
[Small parts used in steps 12 - 16 are included in front part (B) bag.]

12 Install onto main chassis ③ front axle mount ②, joint collar ②, front arm axle A ② as illustrated.

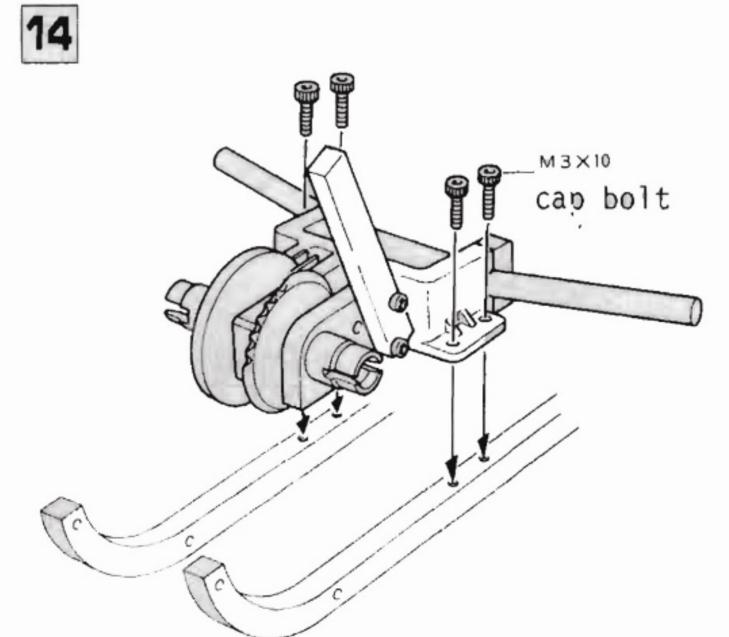
13

Loosen up once and
after setting in place
has been firmished,
tighten so there will
not be too much play

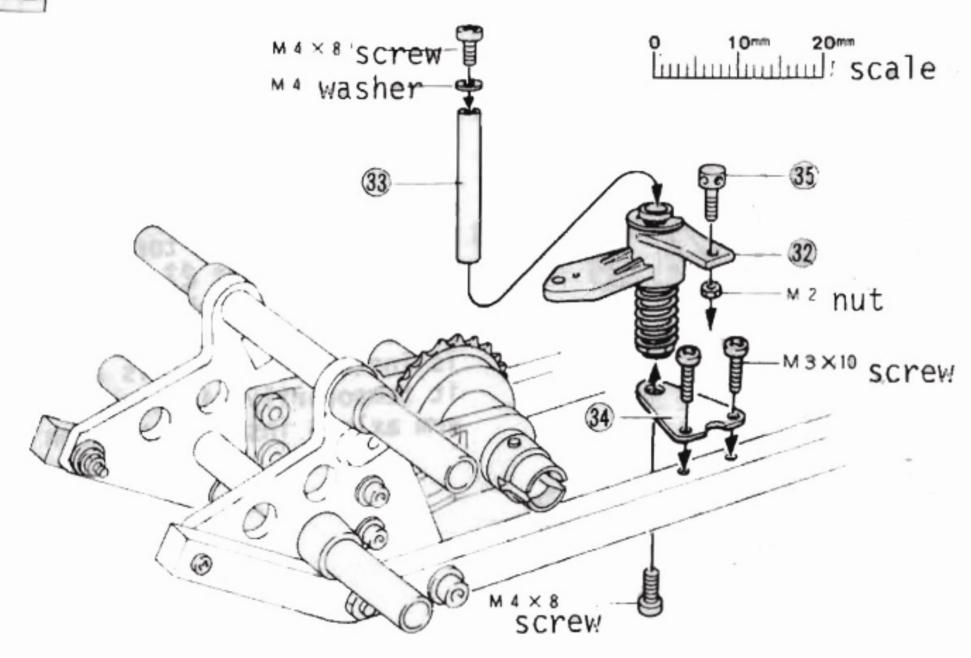
on both side.



13 Install completed torque clutch part onto front axle mount 2). For adjusting, the hole is made in oblong shape. The correct position is adjusted at the time the chain is installed. In this assembly step, have it temporarily tightened. Have the front arm axle B inserted through the mount.

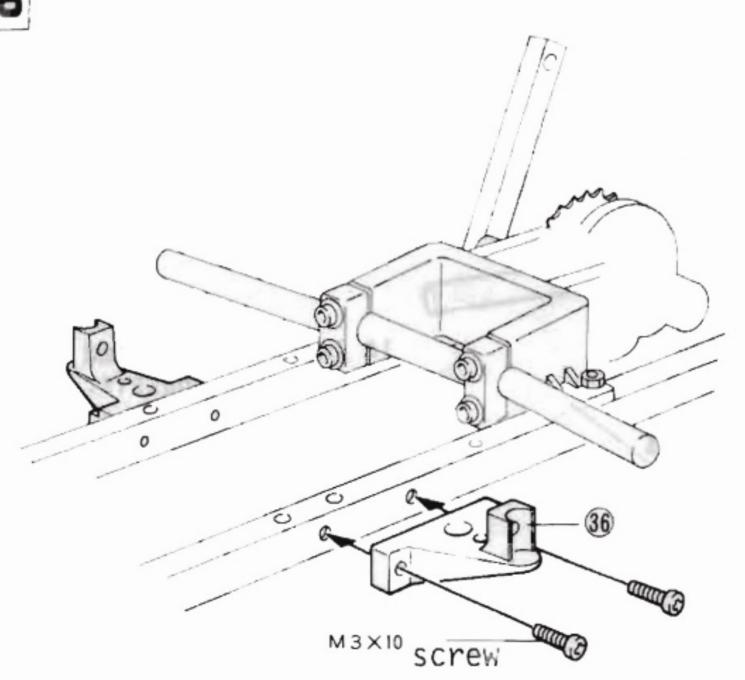


14 Install completed rear axle part onto the chassis.

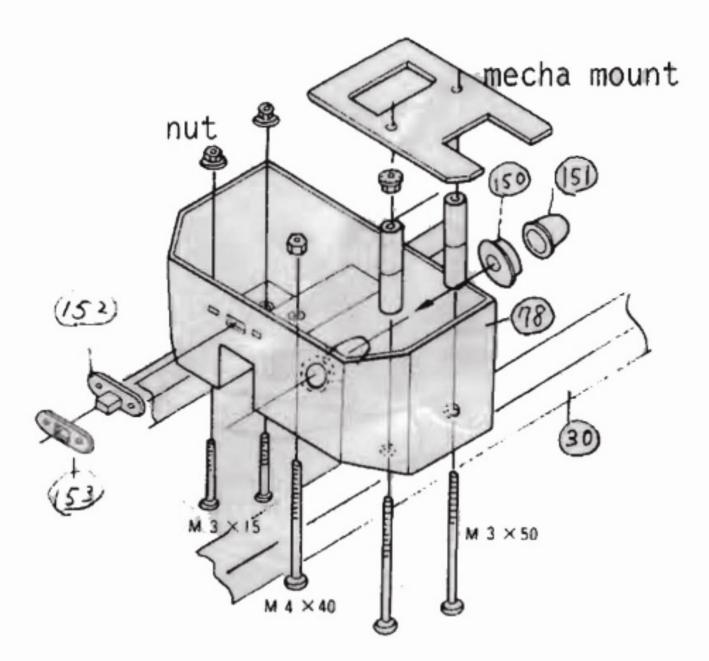


15 Install linkage guide 39 onto servo saver 32 it will move freely. Next install servo saver 32 onto servo saver installation hardware 34 and then onto the chassis.



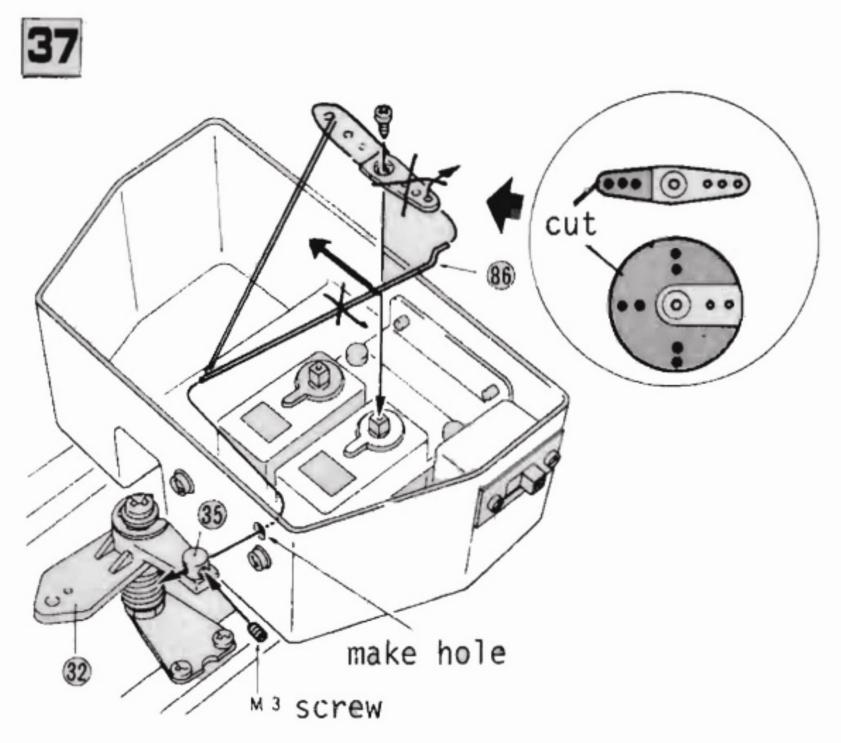


16 Install side member 36 onto main chassis.

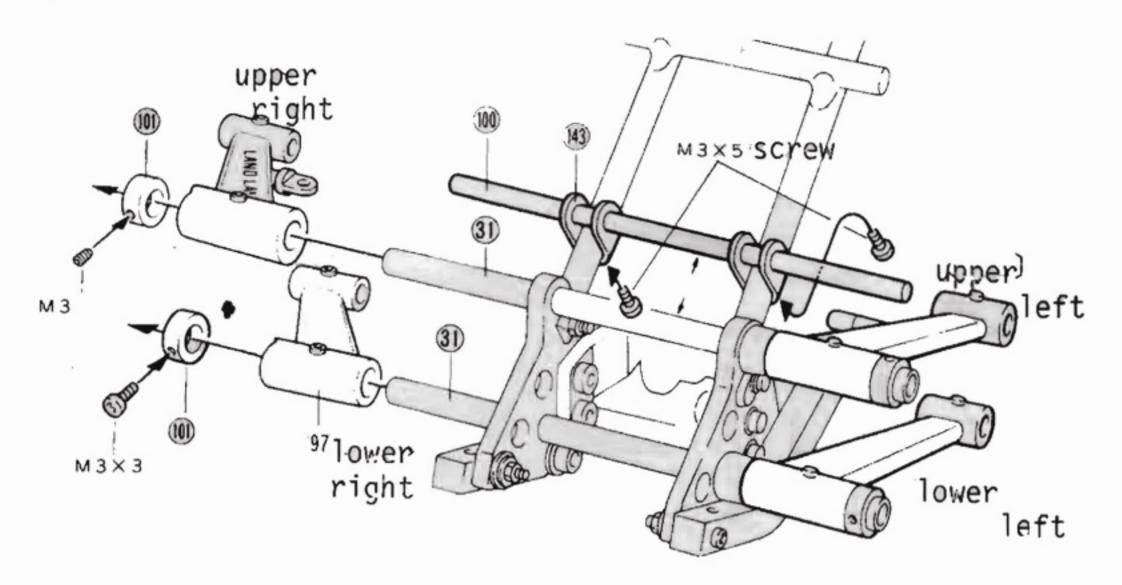


31 Install servo onto mecha mount and then install mecha box 78 onto chassis 30. Cement rod boots (151) to rod boots ring (150) and cement rod boots to mecha box hole as illustrated. Install switch boots (152) and switch plate (153) to mecha box with switch.

Please disregard No. 31, 32, 33, 34 & 36 in the instruction and refer above drawing No. 31.



37 Install linkage rod onto servo horn and then set the servo horn 180° reverse side as illustrated.



44 Making sure of top right and top left sides of the front suspension arm that was assembled in step 43, set the arms into place as illustrated. Set 100 80 stopper into place to the point that it does not have excess play and make so that suspension arm will move up and down smoothly.